Optimizing Signal Graphs for Functional-Reactive Programs

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elm

the best of functional programming in your browser

writing great code should be easy ... now it is

try or install



For me, primarily a teaching tool, using it for:

beginning programmers at high school level



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- a declarative programming course at university



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A Simple Elm Program

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... and functions:

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main = Signal.map view behavior

A Simple Elm Program ... and its Signal Graph

Signals . . . behavior : Signal (Time, (Int, Int)) behavior = timestamp (Signal.sampleOr and functions: view(t,(x,y)) =let $(cx, cy) = (100 * \cos t, 100 * \sin t)$ (px, py) = (toFloat x - 100, 100 in collage 200 200 [move (*cx*, *cy*) (fil traced defaultL

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Why?

 communication flow structure / overhead



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- avalanches of 'no-update's



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How?

 as a start, collapse chains of nodes



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How?

- as a start, collapse chains of nodes
- by some kind of syntactic fusion ?



Fusion of Signal Primitives

A simple case:

Signal.map f (Signal.map g signal) \rightsquigarrow Signal.map ($f \ll g$) signal

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```
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\xrightarrow{\sim}
Signal.map (f \ll g) signal
```

Further candidates:

- Fime.timestamp
- Signal.dropRepeats
- Signal.filter
- Signal.filterMap
- Signal.foldp

Problems with Syntactic Fusion

A not so simple case:

Signal.map f (Signal.foldp g k signal) $\xrightarrow{\sim}$???

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Actually detecting fusable chains:

 $signal_1 = Signal.map \ g \ signal$ $signal_2 = Signal.map \ f \ signal_1$ -- inline $signal_1$? **Problems with Syntactic Fusion**

A not so simple case:

Signal.map f (Signal.foldp g k signal) → ???

Actually detecting fusable chains:

$$\begin{split} \textit{signal}_1 &= \texttt{Signal.map} \ \textit{g} \ \textit{signal}\\ \textit{signal}_2 &= \texttt{Signal.map} \ \textit{f} \ \textit{signal}_1 & -- \text{ inline} \ \textit{signal}_1?\\ \textit{signal}_3 &= \texttt{do-whatever-with} \ \textit{signal}_1 & -- \text{ what now}? \end{split}$$

Fact: Signal graphs in Elm are static (once created).

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Conceptually, 3 phases in executing an Elm program:

- 1. compiling Elm to JavaScript;
- running some JavaScript, setting up the signal graph of nodes, which embed further JavaScript;
- 3. sending events to the signal graph, running the JavaScript embedded in nodes.

Signal graph construction: 'red' code. Pure functions in nodes: 'green' code.

$$\begin{aligned} \text{view} (t, (x, y)) &= \\ \text{let} \\ (cx, cy) &= (100 * \cos t, 100 * \sin t) \\ (px, py) &= (\texttt{toFloat} \ x - 100, 100 - \texttt{toFloat} \ y) \\ \text{in} \\ \texttt{collage} \ 200 \ 200 \ [\texttt{move} \ (cx, cy) \ (\texttt{filled} \ \texttt{red} \ (\texttt{circle} \ 10)), \\ \texttt{traced} \ \texttt{defaultLine} \ (\texttt{path} \ [(cx, cy), \\ (px, py)])] \end{aligned}$$

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And there can be some 'yellow' code as well.

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- 1. Wait until all 'red' (and maybe some 'yellow') JavaScript code has run.
- 2. Traverse and shrink the signal graph, potentially moving around 'green' JavaScript function objects (which might reference 'yellow' ones).
 - Create 'fat nodes' that do the work of a whole chain of nodes,
 - but that do short-circuit when appropriate (and use iteration instead of function calls).







Sounds easy. Well, yes, but as always the devil is in the details. For example, it turns out JavaScript is an imperative language with mutable state...

So, Does it Work?

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Open:

 evaluate impact on performance (beyond anecdotal) So, Does it Work? - Yes!



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- impact on debugging, hot-swapping?

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- impact on debugging, hot-swapping?

. . .

- deeper fusion (of 'green' functions)?
- other optimizations,